

Lecture 9

* HW1 due in 1 week.

RECAP

Definition (Efficient PAC learning)

A hypothesis class \mathcal{H} is PAC-learnable if there is a learning algorithm A with the following property: for every $\epsilon, \delta \in (0, 1)$, every distribution D over $\{X\}^d$ (where X is typically $\{0, 1\}^k$ or \mathbb{R}), and every $h^* \in \mathcal{H}$, if A is given access to example oracle $\text{Ex}(h^*, D)$ and ϵ, δ , with probability $1 - \delta$, it outputs a hypothesis $h \in \mathcal{H}$ with $R(h) \leq \epsilon$.

\mathcal{H} is efficiently PAC learnable if running time of A is polynomial in $d, \frac{1}{\epsilon}, \frac{1}{\delta}$.

Theorem The class of conjunctions on Boolean literals is efficiently PAC learnable.

Intractability of learning 3-Term DNF

What is a 3-term DNF (Disjunctive Normal Form) ?

3-Term-DNF_d = { T₁ ∨ T₂ ∨ T₃ | T_i is a conjunction
on {x₁, ..., x_d} }

Theorem: 3-term DNF formulae are not efficiently PAC learnable unless RP=NP.

NP: Problems whose solutions are easily verifiable

$$\begin{aligned} \text{3SAT}_d = & (x_1 \vee \bar{x}_2 \vee x_5) \wedge \\ & (x_5 \vee x_6 \vee \bar{x}_7) \wedge \\ & \vdots \\ & (x_{d-2} \vee \bar{x}_{d-1} \vee x_d) \end{aligned}$$

RP: C is in RP if ∃ poly-time algo.
with one-sided error.

3SAT instance is satisfiable, output TRUE w.p. $\geq 2/3$,
not satisfiable, always output FALSE.

NP-Complete: C is in NP, all problems in NP
reducible to C in polynomial time.

— X — X —

Proof of hardness of learning 3-term DNF.

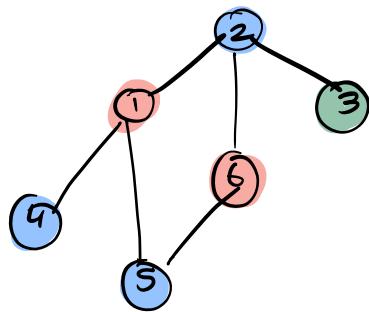
Intuition: Reduce a NP - complete problem to the problem of learning 3-term DNF. The key property we want from mapping is that the answer to decision problem is "yes" if and only if a set of labelled examples is consistent with some hypothesis $h \in H$.

Definition: Let $U = \{(a_1, y_1), \dots, (a_n, y_n)\}$ be labelled set of instances. Let h be any hypothesis. We say that h is consistent with U if $\forall i \in [n], h(a_i) = y_i$.

This recipe of showing hardness is useful quite generally. We now state the NP-complete problem we use.

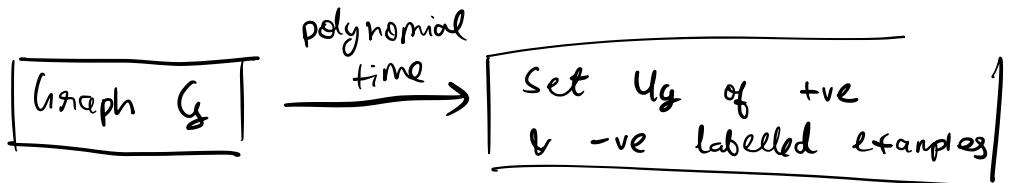
PROBLEM: Graph 3-COLORING

Given an undirected graph $G = (V, E)$ with vertex set $V = \{1, \dots, d\}$, is there an assignment from every vertex $v \rightarrow \{R, B, G\}$ s.t. for every edge $e \in E$, the endpoints of e are assigned different colors?



Graph 3-coloring is NP-complete.

Reduction



We will show that given G , we can construct U_g s.t. U_g is consistent with some $h \in H$ if and only if G is 3-colorable.

Let's see why this is sufficient.

Define :

D : Uniform on U_g

$E(h^*, D)$: Pick a point uniformly at random from U_g .

$\delta = 1/3$

$$\varepsilon = \frac{1}{2|U_g|}$$

ALGORITHM.

1. Given instance of 3-COLOR, construct set U_g .
2. Use PAC-learning algorithm A for 3-term DNF with $E + (h^*, D)$, $\delta = 1/3$, $\epsilon = \frac{1}{2|U_g|}$.
3. Let h be the 3-term DNF returned by A .
4. If h is consistent with U_g
5. return "yes"
6. else
7. return "no"

Note that D is uniform over set of size $|U_g|$.

$$\therefore \epsilon = \frac{1}{2|U_g|} \text{ & } R(h) < \epsilon$$

$\Rightarrow h$ is consistent with set U_g .

If A succeeds, it must return consistent hypothesis.

Therefore, all that remains is to show we

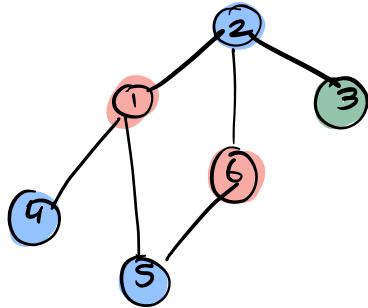
can construct U_g s.t. there is some consistent hypothesis $h \in H$ if and only if g is 3-colorable.

Constructing U_g

$$U_g = U_g^+ \cup U_g^-$$

U_g^+ : +ve examples

U_g^- : -ve examples



$$U_g^+, |U_g^+| = |\mathcal{V}|$$

$$(v(1), +) = ((0, 1, 1, 1, 1, 1), +)$$

$$(v(2), +) = ((1, 0, 1, 1, 1, 1), +)$$

:

$$(v(6), +) = ((1, 1, 1, 1, 1, 0), +)$$

$$U_g^-, |U_g^-| = |\mathcal{E}|$$

$$(e(1), -) = ((0, 0, 1, 1, 1, 1), -)$$

$$(e(4), -) = ((0, 1, 1, 0, 1, 1), -)$$

:

$$(e(5), -) = ((1, 1, 1, 1, 0, 0), -)$$

Part 1: 3-colorable \Rightarrow \exists a consistent 3-term DNF

$$3\text{-term DNF } \phi = T_R \vee T_B \vee T_U$$

R: set of all vertices colored Red.

B: } similarly
U: }

T_R : conjunctions of all variables whose index does not appear in R.

$$T_R = x_2 \wedge x_3 \wedge x_4 \wedge x_5$$

Similarly for T_B & T_U ,

$$T_B = x_1 \wedge x_3 \wedge x_6$$

$$T_U = x_1 \wedge x_2 \wedge x_4 \wedge x_5 \wedge x_6$$

* For each $i \in R$

example $v(i)$ must satisfy T_R because x_i does not appear in T_R .

* Further no $e(i,j) \in U_j^-$ can satisfy T_R .

\rightarrow both i & j cannot be colored red, one if x_i or x_j must appear in T_R .

But $e(i,j)$ has 0 values for both x_i & x_j .

$\therefore T_R$ cannot be satisfied by $e(i,j)$.

$\therefore \phi = T_R \vee T_B \vee T_U$ is consistent.

Part 2: 3-term DNF \Rightarrow 3-colorable

$$\phi = T_R \vee T_B \vee T_Y$$

for a vertex i : if $v(i)$ satisfies T_R , color i Red
" " T_B , " " Blue
" " T_Y , " " Green

(Break any ties arbitrarily)

Since formula is consistent, every $v(i)$ must satisfy at least one of T_R, T_B, T_Y

\therefore every vertex is assigned a color.

Claim: coloring is valid 3-coloring.

Proof: If $i \neq j$ ($i \neq j$) are assigned the same color (say Red), both $v(i)$ & $v(j)$ satisfy T_R .

$$v(i) = (1, \dots, 0, \underbrace{\dots}_{\text{ith coordinate}} 1)$$
$$v(j) = (1, \dots, 1, \dots, 0, \dots)$$

\therefore Since i th bit of $v(i)$ is 0
& i th bit of $v(j)$ is 1

\Rightarrow neither x_i nor \bar{x}_i appears in T_R .

$$e(i,j) = (1, \dots, 0, \dots, 0, \dots)$$

$e(i,j)$ & $v(j)$ differ only in i th coordinate

\therefore if $v(j)$ satisfies T_R , so does $e(i,j)$

$e(i,j)$ should be labelled true

$$\Rightarrow e(i,j) \notin U_0^-$$

$$\therefore (i, j) \notin E.$$

■

Using 3-CNF formulae to avoid intractability

So far, we've restricted the learning algorithm to output a hypothesis from the same class it was learning.

What if we allow the algorithm to output a hypothesis from a different, more expressive class?

Distributive law:

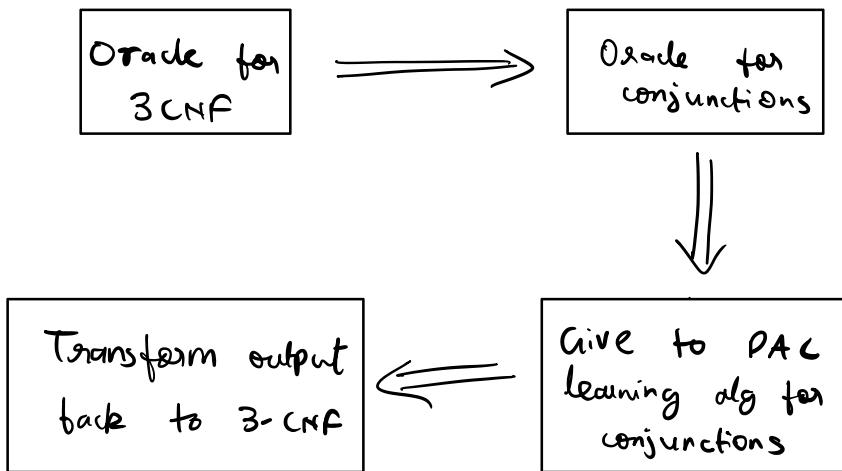
$$(u \wedge v) \vee (w \wedge x) = (u \vee w) \wedge (u \vee x) \\ \wedge (v \vee w) \wedge (v \vee x)$$

We can represent any 3-term DNFd $\phi = T_1 \vee T_2 \vee T_3$
by a 3-CNFd $\psi = \bigwedge_{\substack{u \in T_1 \\ v \in T_2 \\ w \in T_3}} (u \vee v \vee w)$

This is a 3CNF (Conjunctive Normal Form).

Theorem: The class of 3-CNF formulae is efficiently PAC learnable.

Proof: We will reduce the problem of PAC learning 3-CNF formulae to the problem of PAC learning conjunctions.



Idea: Regard 3-CNF formulae as a conjunction over a new & larger variable set.

Transformation: For every triple of literals u, v, w over the original variable set $\{x_1, \dots, x_d\}$ the new variable set contains a variable $y_{u,v,w} = u \vee v \vee w$. When $u = v = w$, $y_{u,v,w} = u$, so all original variables are in new set.

$$\# \text{ of variables} = (2d)^3 = O(d^3)$$

Transforming oracles: For any assignment $a \in \{0,1\}^d$ to original variable, we can in $O(d^3)$ time compute assignment to new variable set $\{y_{u,v,w}\}$.

Note that any 3-CNF over x_1, \dots, x_d
 \equiv a simple conjunction over $\{y_{u,v,w}\}$.
 (replacing any clause $u \vee v \vee w$ by $y_{u,v,w}$)

∴ we can run algorithm for conjunctions.
 We can transform the output h' of the algorithm
 back to a 3-CNF h , by expanding any
 occurrence of $y_{u,v,w}$ by $(u \vee v \vee w)$.

Claim If h^* and D are the target 3-CNF
 formula and the distribution over $\{0,1\}^d$, and
 h'^* and D' are the corresponding conjunction over
 $y_{u,v,w}$ and the corresponding distribution over
 $y_{u,v,w}$, then if h' has error $\leq \varepsilon$ with respect
 to h^* and D' , then h has error $\leq \varepsilon$ with
 respect to h^* and D .

Proof Our transformation of instances is one \rightarrow one

$$\text{if } a_1 \rightarrow a'_1 \text{ & } a_2 \rightarrow a'_2$$

$$a_1 \neq a_2 \Rightarrow a'_1 \neq a'_2$$

∴ our reduction is done

Important takeaway The choice of representation /
hypotheses can make the difference between
efficient algorithms & intractability! Going to more
expressive hypothesis classes (3 term DNF \rightarrow 3 CNF)
makes learning efficient! Statistically, learning over
a richer hypothesis class can never help if
you know your target hypothesis lies in
smaller class, but computationally the picture
is very different!